

Deep Learning

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A: A branch of Machine Learning







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- Q: To what kind of problems it can be applied?





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- A: To all problems suitable for Machine Learning



- Q: What is Deep Learning?
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A: Neural Networks



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- A: Neural Networks
- Q: Why "Deep"?
- A: because it exploits Deep Neural Networks, composed by many nested layers of neurons



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- A: Neural Networks
- Q: Why "Deep"?
- A: because it exploits Deep Neural Networks, composed by many nested layers of neurons
 - because it exploits deep features of data, that is features extracted from other features



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ML recap



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There are problems that are difficult to address with traditional programming techniques:

- classify a document according to some criteria (e.g. spam, sentiment analysis, ...)
- compute the probability that a credit card transaction is fraudulent
- recognize an object in some image (possibly from an inusual viewpoint, in new lighting conditions, in a cluttered scene)

Typically the result is a weighted combination of a large number of parameters, each one contributing to the solution in a small degree.



...

The Machine Learning approach

Suppose to have a set of input-output pairs (training set)

 $\{\langle x_i, y_i \rangle\}$

the problem consists in guessing the map $x_i \mapsto y_i$

The M.L. approach:

- describe the problem with a model depending on some parameters Θ (i.e. choose a parametric class of functions)
- define a loss function to compare the results of the model with the expected (experimental) values
- **optimize** (fit) the parameters Θ to reduce the loss to a minimum



You have some points on the plane and you want to fit a line through them

- Step 1 Fix a parametric class of models. For intance linear functions y = ax + b; *a* and *b* are the parameters of the model
- Step 2 Fix a way to decide when a line is better than another (loss function) For instance, mean square error (mse)
- Step 3 Try to tune the parameters in order to reduce the loss (training).







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So, we use **iterative** techniques (typically, gradient descent) to progressively approximate the result.

This form of iteration over data can be understood as a way of progressive learning of the objective function based on the experience of past observations.



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Using gradients

Goal: minimize a loss function E over (fixed) training samples:

$$\Theta(w) = \sum_i E(o(w, x_i), y_i)$$

See how it changes according to small perturbations $\Delta(w)$ of the parameters w: this is the gradient

$$abla_w[\theta] = \left[\frac{\partial \Theta}{\partial w_1}, \dots, \frac{\partial \Theta}{\partial w_n}\right]$$

of Θ w.r.t. w.

The gradient is a vector pointing in the direction of steepest ascent.



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A bit of taxonomy



Different types of Learning Tasks

- supervised learning:
 - inputs + outputs (labels)
 - classification
 - regression
- unsupervised learning:
 - just inputs
 - clustering
 - component analysis
 - anomaly detection autoencoding
- reinforcement learning
 - actions and rewards
 - learning long-term gains
 - planning





Classification vs. Regression

Two forms of supervised learning: $\{\langle x_i, y_i \rangle\}$



y is discete: $y \in \{\bullet, +\}$ y is (conceptually) continuous

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Many different techniques

- Different ways to define the models:
 - decision trees
 - linear models
 - neural networks

- ...

- Different error (loss) functions:
 - mean squared errors
 - logistic loss
 - cross entropy
 - cosine distance
 - maximum margin

- ...





Neural Networks





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Neural Network

A network of (artificial) neurons



Each neuron takes multiple inputs and produces a single output (that can be passed as input to many other neurons).





The artificial neuron





Each neuron (!) implements a logistic regressor

 $\sigma(wx+b)$



Different activation functions

The activation function is responsible for threshold triggering.



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The cortical neuron



- the dendritic tree of the cell collects inputs from other neurons, that get summed together
- when a triggering threshold is exceeded, the Axon Hillock generate an impulse that get transmitted through the axon to other neurons.





A comparison with the cortical neuron

Artificial Neural Networks (ANN)



Slide credit : Andrew L. Nelson 🗦 🔊 ९ ९



Some figures for human brains

- number of neurons: $\sim 2 \cdot 10^{10}$
- **>** switching time for neuron: \sim .001 s. (slow!)
- ▶ synapses (connections) per neuron: $\sim 10^{4-5}$
- \blacktriangleright time to recognize an image: \sim .1 s.

```
not too deep (< 100) very high parallelism
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▶ to understand, via simulation, how the brain works

 to investigate a different paradigm of computation very far from traditional programming languages

to solve practical problems difficult to address with algorithmic techniques

useful even if the brain works in a different way



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Network topologies



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If the network is acyclic, it is called a feed-forward network.

If it has cycles it is called recurrent.



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In a feed-forward network, neurons are usually organized in layers.



If there is more than one hidden layer the network is deep, otherwise it is called a shallow network.



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Main layers in feed-forward networks: dense layer

Dense layer: each neuron at layer k-1 is connected to **each** each neuron at layer k.



A single neuron:

$$I^n \cdot W^n + B^1 = O^1$$

the operation can be vectorized to pruduce *m* outputs in parallel:

$$I^n \cdot W^{n \times m} + B^m = O^m$$

dense layers usually work on flat (unstructured) inputs

the order of elements in input is irrelevant

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Main layers in feed-forward networks: convolutional layer

Convolutional layer: each neuron at layer k - 1 is connected via a parametric **kernel** to a fixed subset of neurons at layer k. The kernel is convolved over the whole previous layer.



- 1. move the kernel K over a portion M of the input of equal size
- 2. compute the dot product $M \cdot K$ and possibly add a bias
- 3. shift the kernel and repeat

The dimension of the output only depends from the number of times the kernel is applied.

Input is structured, and the structure is reflected in the output.



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The weights W_k are the parameters of the model: they are **learned** during the training phase.

The number of neurons and the way they are connected together are hyper-parameters: they are chosen by the user and **fixed** before training may start.

Other important hyper-parameters govern training such as learning rate, batch-size, number of ephocs an many others.



Features and deep features



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Any individual measurable property of data useful for the solution of a specific task is called a feature.

Examples:

- Medical Diagnosis: information about the patient (age, clinical history, ...), symptoms, physichal examination, results of medical tests, ...
- Meteo forecasting: humidity, pression, temperature, wind, rain, snow, ...
- Image Processing: raw pixels, combination of adjacent pixels, ...



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- Signals: raw input collected from sensors
- Data: meaningful but not focused
- Features: meaningful and focused



Deep learning, in deeper sense

Discovering good features is a **complex task**.

Why not delegating the task to the machine, learning them?

Deep learning exploits a *hierarchical organization* of the learning model, allowing complex features to be computed in terms of simpler ones, through non-linear transformations.



Each layer synthesize new features in terms of the previous ones.



• Knowledge-based systems: take an expert, ask him how he solves a problem and try to mimic his approach by means of logical rules



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- Knowledge-based systems: take an expert, ask him how he solves a problem and try to mimic his approach by means of logical rules
- **Traditional Machine-Learning**: take an expert, ask him what are the features of data relevant to solve a given problem, and let the machine learn the mapping
- Deep-Learning: get rid of the expert



Relations between research areas



Picture from "Deep Learning" by Y.Bengio, I.Goodfellow e A.Courville, MIT Press.

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Components trained to learn



Picture from "Deep Learning" by Y.Bengio, I.Goodfellow e A.Courville, MIT Press.

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Diving into DL



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[demo]



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- understand the different layers, and their purpose
- understand how layers can be organized in **relevant** architectures
- understand the different possible **applications** of DL, and their specific solutions
- understand the main issues, problems and costs



- TensorFlow/Keras, Google Brain
- PyTorch, Facebook
- MXNET, Apache

We shall mostly use Keras.



Legacy 1958 perceptron 1975 backpropagation 1980 convolutional layers 1992 Max-pooling 1997 LSTM

Extremely slow progress



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The Deep Learning revolution

2011	Google Brain foundation	2016	Residual connections
2012	ReLU and Dropout	2017	PyTorch release
2012	ImageNet Competition	2017	Mask-RCNN
2013	DQN	2017	PPO
2014	GANs	2018	Transformers
2014	Attention	2018	BERT/GPT
2014	Inception v1	2018	Soft Actor Critic
2015	Tensorflow release	2020	OpenAl Jukebox
2015	Keras release	2021	MXNet release
2015	Batchnormalization	2021	TFP release
2015	YOLO v1	2022	Keras-CV
2015	OpenAI foundation	2022	Dall·E 2, Imagen

Just to mention a few milestones ...

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Frameworks and Libraries

2011	Google Brain foundation

- 2012 | ReLU and Dropout
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- 2017 Mask-RCNN
- 2017 | PPO
- 2018 Transformers
- 2018 | BERT/GPT
- 2018 | Soft Actor Critic
- 2020 OpenAl Jukebox
- 2021 MXNet release
- 2021 **TFP release**
- 2022 Keras-CV
- 2022 Dall·E 2, Imagen



Some popular technical improvements

2011 Google Brain foundation	on
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- 2012 ReLU and Dropout
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- 2014 Attention
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- 2015 BatchNormalization
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2016 **Residuality** & Resnet PyTorch release 2017 Mask-RCNN 2017 2017 PPO 2018 Transformers 2018 BERT/GPT Soft Actor Critic 2018 2020 **OpenAl Jukebox** 2021 MXNet release 2021 TFP release 2022 Keras-CV Dall-E 2, Imagen 2022



Important Architectures

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- 2022 Dall·E 2, Imagen



Deep Reinforcement Learning algorithms

2011 Google	Brain	foundation
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- 2014 | GANs
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Brackthrough applications

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The situation at the beginning of the century



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The deep learnig era



See my blog for a short historical perspective.



structure of the course

- books, tutorials and blogs
- software
- examination
- office hours



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Structure of the course

Frontal lessons intermixed with demos + labs

- Domains of application of Deep Learning
- Expressiveness
- Backpropagation
- Convolutional Networks
- Understanding CNNs
- Object Detection and Segmentation
- Autoencoders
- Generative Adversarial Networks
- Recurrent Networks
- LSTM, Attention, Transformers
- Reinforcement Learning



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► Dive into deep learning (D2L)

 Y.Bengio, I.Goodfellow and A.Courville. Deep Learning, MIT Press to appear.



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Possible to study on online material (fast updating):

- Tensorflow tutorials
- Towards data science
- Keras blog. By F.Chollet.
- Machine learning tutorial with Python
- Deep Learning Tutorial. LISA lab. University of Montreal.
- a lot of interesting lessons and seminars on youtube
- a lot of material on github



The State of the Art site! (papers with code)

- Tensor flow dataset
- Kaggle Datasets
- Many standard datasets for image processing: Pascal VOC, Coco, . . .
- Face detection and recongition: CelebA, Labeled Faces in the Wild, ...
- Biomedical challenges
- Amazon Datasets
- ...

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At each exam sessions you will receive a project assignement that you are supposed to complete in **7 days**.

You are supposed to deliver:

the code source (Keras/TensorFlow) in the form of a single, commented pyhton notebook

The work will be evaluated according to

- 1. 80% : comparative evaluation of results (measured in an objective way according to given metrics);
- $2.\ 20\%$: descriptive quality of the notebook

You may possibly integrate the grade with an oral examination.



Office hours: On appointment

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